Problem 1. (20 pts.) Solve the following differential equations.

a. (8 pts.) y'' + 4y' + 8y = 0

Characteristic equation: $r^2 + 4r + 8 = 0 \Rightarrow r = \frac{-4 \pm \sqrt{4^2 - 4(1)(8)}}{2(1)} = \frac{-4 \pm \sqrt{-16}}{2} = \frac{-4 \pm 4i}{2} = -2 \pm 2i$ [3 pts.] Therefore, $y = c_1 e^{-2x} \cos(2x) + c_2 e^{-2x} \sin(2x)$] [5 pts.]

b. (12 pts.) $y^{(4)} + 4y'' = 0$

Characteristic equation: $r^4 + 4r^2 = 0 \Rightarrow r^2 (r^2 + 4) = 0 \Rightarrow r = 0$ (double root), $r = \pm 2i = 0 \pm 2i$ [4 pts.] Therefore, $y = c_1 e^{0x} + c_2 x e^{0x} + c_3 e^{0x} \cos(2x) + c_4 e^{0x} \sin(2x)$ or $y = c_1 + c_2 x + c_3 \cos(2x) + c_4 \sin(2x)$] [8 pts.]

Problem 2. (25 pts.) Solve the following initial value problem:

$$y'' + y' = 3 + 4\sin(x), \quad y(0) = 0, \quad y'(0) = 1.$$

Step 1. Find y_c by solving the homogeneous d.e. y'' + y' = 0. Characteristic equation: $r^2 + r = 0 \Rightarrow r(r+1) = 0 \Rightarrow r = 0$ or r = -1. Therefore, $y_c = c_1 e^{0x} + c_2 e^{-x} = c_1 + c_2 e^{-x}$. 5 pts.

Step 2. Find y_p . You can use either of the following methods.

Method 1: Undetermined Coefficients. The nonhomogeneous term in the de is $3 + 4\sin(x)$. To handle the constant 3, a polynomial of degree 0, we should guess that y_p contains a polynomial of degree 0: A. This guess duplicates the term c_1 in y_c , so we should multiply this part of the guess by x to get Ax.

To handle the $4\sin(x)$ term, we should guess that y_p contains a combination of sine and cosine with the same coefficient of x: $B\sin(x) + C\cos(x)$. This guess does not duplicate any term in y_c , so there is no need to multiply this part of the guess by x.

Therefore, the complete guess is $y_p = Ax + B\sin(x) + C\cos(x)$. 7 pts.

 $y = Ax + B\sin(x) + C\cos(x) \Rightarrow y' = A + B\cos(x) - C\sin(x) \Rightarrow y'' = -B\sin(x) - C\cos(x).$ Therefore, the left side of the d.e. is $y'' + y' = [-B\sin(x) - C\cos(x)] + [A + B\cos(x) - C\sin(x)] = A + (-B - C)\sin(x) + (B - C)\cos(x)$

We want this to equal the nonhomogeneous term $3 + 4\sin(x)$: $A + (-B - C)\sin(x) + (B - C)\cos(x) = 3 + 4\sin(x) \Rightarrow A = 3, -B - C = 4, B - C = 0$ $\Rightarrow A = 3, B = -2, C = -2$. Thus, $y_p = 3x - 2\sin(x) - 2\cos(x)$. 8 pts.

Method 2: Variation of Parameters. From y_c we obtain two independent solutions of the homogeneous d.e: $y_1 = e^{0x} = 1$ and $y_2 = e^{-x}$. I pt. The Wronskian is given by

$$\begin{split} W(x) &= \begin{vmatrix} y_1 & y_2 \\ y'_1 & y'_2 \end{vmatrix} = \begin{vmatrix} 1 & e^{-x} \\ 0 & -e^{-x} \end{vmatrix} = 1 \left(-e^{-x} \right) - 0 \left(e^{-x} \right) = -e^{-x}. \ 2 \text{ pts.} \\ u_1 &= \int \frac{-y_2 f(x)}{W(x)} \, dx = -\int \frac{e^{-x} \left(3 + 4\sin(x) \right)}{-e^{-x}} \, dx = \int \left(3 + 4\sin(x) \right) \, dx = 3x - 4\cos(x). \ 5 \text{ pts.} \\ u_2 &= \int \frac{y_1 f(x)}{W(x)} \, dx = \int \frac{1 \left(3 + 4\sin(x) \right)}{-e^{-x}} \, dx = -\int e^x \left(3 + 4\sin(x) \right) \, dx = -\left\{ -3e^x + 2e^x \left[\sin(x) - \cos(x) \right] \right\} = e^x \left[3 - 2\sin(x) + 2\cos(x) \right] \text{ using formula 49 from the integral table). } \ 5 \text{ pts.} \end{split}$$

Therefore, $y_p = u_1 y_1 + u_2 y_2 = [3x - 4\cos(x)](1) + \{e^x [3 - 2\sin(x) + 2\cos(x)]\}(e^{-x}) = 3x - 4\cos(x) + 3 - 2\sin(x) + 2\cos(x) = 3x - 2\sin(x) - 2\cos(x) + 3$ [2 pts.]

Step 3. $y = y_c + y_p$, so $y = c_1 + c_2 e^{-x} + 3x - 2\sin(x) - 2\cos(x)$ [2 pts.] (If you used the Method of Variation of Parameters, you can combine the 3 from y_p with the c_1 from y_c .)

Step 4. Use the initial conditions to determine the values of
$$c_1$$
 and c_2 .
 $y = c_1 + c_2 e^{-x} + 3x - 2\sin(x) - 2\cos(x) \Rightarrow y' = -c_2 e^{-x} + 3 - 2\cos(x) + 2\sin(x)$
 $y(0) = 0 \Rightarrow c_1 + c_2 e^0 + 3(0) - 2\sin(0) - 2\cos(0) = 0 \Rightarrow c_1 + c_2 = 2.$
 $y'(0) = 1 \Rightarrow -c_2 e^0 + 3 - 2\cos(0) + 2\sin(0) = 1 \Rightarrow -c_2 + 1 = 1 \Rightarrow c_2 = 0.$
 $c_1 + c_2 = 2, \ c_2 = 0 \Rightarrow c_1 = 2, \ c_2 = 0.$ 3 pts. Therefore, $y = 2 + 3x - 2\sin(x) - 2\cos(x)$

Problem 3. (20 pts.) Consider a free (unforced), damped mass-spring system with mass m = 1 kg, damping constant c = 4 N·s/m, and spring constant k = 5 N/m. Assume that x(0) = -1 m and x'(0) = 3 m/s.

a. (16 pts.) Find the position function x(t).

The d.e. describing a mass-spring system is $mx'' + cx' + kx = F_e(t)$. 3 pts. In this problem, $m = 1, c = 4, k = 5, \text{ and } F_e(t) = 0$. Therefore, we have x'' + 4x' + 5x = 0. 2 pts. The characteristic equation for this d.e. is $r^2 + 4r + 5 = 0 \Rightarrow$ $r = \frac{-4 \pm \sqrt{4^2 - 4(1)(5)}}{2(1)} = \frac{-4 \pm \sqrt{-4}}{2} = \frac{-4 \pm 2i}{2} = -2 \pm i$. 4 pts. Therefore, $x = c_1 e^{-2t} \cos(t) + c_2 e^{-2t} \sin(t)$. 5 pts. $x = c_1 e^{-2t} \cos(t) + c_2 e^{-2t} \sin(t) \Rightarrow x' = c_1 \left[-2e^{-2t} \cos(t) - e^{-2t} \sin(t) \right] + c_2 \left[-2e^{-2t} \sin(t) + e^{-2t} \cos(t) \right] + c_2 \left[-2e^0 \sin(0) + e^0 \cos(0) + c_2 e^0 \sin(0) + c_2 e^0 \sin(0) = c_1 \text{ and } 3 = c_1 \left[-2e^0 \cos(0) - e^0 \sin(0) \right] + c_2 \left[-2e^0 \sin(0) + e^0 \cos(0) \right] = -2c_1 + c_2 \Rightarrow c_1 = -1, c_2 = 1$. Therefore, $\boxed{x = -e^{-2t} \cos(t) + e^{-2t} \sin(t)}$.

b. (4 pts.) Write the solution from part a in the form $x(t) = Ce^{-pt} \cos(\omega_1 t - \alpha)$

$$x = c_1 e^{-2t} \cos(t) + c_2 e^{-2t} \sin(t) = e^{-2t} [c_1 \cos(t) + c_2 \sin(t)] = e^{-2t} [C \cos(t - \alpha)]$$

$$C = \sqrt{c_1^2 + c_2^2} = \sqrt{(-1)^2 + 1^2} = \sqrt{2} \ 2 \text{ pts.}$$

Because $c_1 < 0$ we have $\alpha = \pi + \tan^{-1} (c_2/c_1) = \pi + \tan^{-1} (-1) = \pi - \pi/4 = \frac{3\pi}{4} \ 2 \text{ pts.}$
Therefore, $\boxed{x = \sqrt{2}e^{-2t} \cos\left(t - \frac{3\pi}{4}\right)}$

Problem 4. (20 pts.) Solve the system $\begin{cases} x' = y \\ y' = -x + 2y \end{cases}$

Take the derivative of both sides of the first d.e. in the system: $x' = y \Rightarrow x'' = y'$. The second d.e. in the system is y' = -x + 2y. Therefore, x'' = -x + 2y. From the first d.e. in the system, y = x', so we have x'' = -x + 2x' [8 pts.] $x'' = -x + 2x' \Rightarrow x'' - 2x' + x = 0$. Characteristic equation: $r^2 - 2r + 1 = 0 \Rightarrow (r - 1)^2 = 0 \Rightarrow r = 1$ (double root) $\Rightarrow x = c_1 e^t + c_2 t e^t$. [8 pts.] The first d.e. in the given system says y = x', so $y = c_1 e^t + c_2 [e^t + t e^t]$. Therefore, the solution of the given system is $\boxed{x = c_1 e^t + c_2 t e^t, y = c_1 e^t + c_2 [e^t + t e^t]}$ [4 pts.]