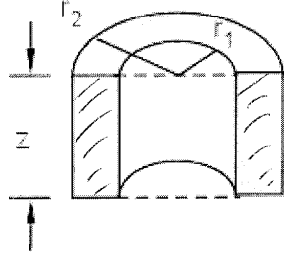


1. (35%) A section of a cylinder is by $1 \leq r \leq 2$, $0 \leq z \leq 2$, $0 \leq \phi \leq \pi$. shown below, A vector field is $\vec{E} = \hat{r}r \cos \phi + \hat{\phi}r \sin \phi$. Verify divergence theorem by calculating:

$$\oiint_S \vec{E} \cdot d\vec{s} = \iiint_V (\nabla \cdot \vec{E}) dv.$$



Solution.

$$1. \nabla \cdot \vec{E} = \frac{1}{r} \frac{\partial}{\partial r} (r \cdot r \cos \phi) + \frac{1}{r} \frac{\partial}{\partial \phi} (r \sin \phi)$$

$$\nabla \cdot \vec{E} = \frac{1}{r} \cdot 2r \cos \phi + \cos \phi$$

$$= 3 \cos \phi$$

$$\iiint (\nabla \cdot \vec{E}) \cdot dv = \int_1^2 \int_0^\pi \int_0^2 3 \cos \phi \cdot r d\phi dr dz$$

$$= 2 \cdot \int_1^2 r dr \int_0^\pi 3 \cos \phi d\phi$$

$$= 0 \cdot \left. \frac{r^2}{2} \right|_1^2 \cdot \sin \phi \Big|_0^\pi = 0$$

$$\oiint \vec{E} \cdot d\vec{s} = \iint_{\text{top}} \vec{E} \cdot d\vec{s} + \iint_{\text{bottom}} \vec{E} \cdot d\vec{s} + \iint_{\text{side}} \vec{E} \cdot d\vec{s} + \iint_{\text{left}} \vec{E} \cdot d\vec{s} + \iint_{\text{right}} \vec{E} \cdot d\vec{s}$$

$$\iint_{\text{top}} \vec{E} \cdot d\vec{s} = \iint (\hat{r}r \cos \phi + \hat{\phi}r \sin \phi) \cdot \hat{z} r dr d\phi = 0$$

$$\iint_{\text{bottom}} \vec{E} \cdot d\vec{s} = 0, \text{ same as above}$$

$$\iint (\hat{r}r \cos \phi + \hat{\phi}r \sin \phi) \cdot \hat{r} r d\phi dz \Big|_{r=2}$$

out side

$$\int_0^2 \int_0^\pi r^2 \cos\phi \, d\phi \, dz \Big|_{r=2} = 4 \int_0^2 dz \int_0^\pi \cos\phi \, d\phi = 0$$

Side
Same for inside surface.

$$\iint_{\text{left}} \vec{E} \cdot d\vec{s} = \int \int (\hat{r} r \cos\phi + \hat{\phi} r \sin\phi) \cdot \hat{\phi} \, dr \, dz \Big|_{\phi=\pi}$$

Left

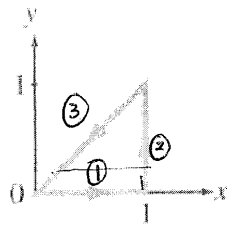
$$= \int_0^2 \int_r^2 r \sin\phi \, dr \, dz \Big|_{\phi=0} = 0$$

$$\iint_{\text{right}} \vec{E} \cdot d\vec{s} = \int \int (\hat{r} r \cos\phi + \hat{\phi} r \sin\phi) \cdot \hat{\phi} \, dr \, dz \Big|_{\phi=0}$$

$$= 0$$

Check out.

2. (35%) Verify Stokes's theorem for the vector field $\vec{A} = \hat{x}y^3 + \hat{y}x^3$ along the contour shown below:



Solution: $\oint \vec{A} \cdot d\vec{l} = \iint (\nabla \times \vec{A}) \cdot d\vec{s}$

$$\oint \vec{A} \cdot d\vec{l} = \int_{\textcircled{1}} \vec{A} \cdot d\vec{l} + \int_{\textcircled{2}} \vec{A} \cdot d\vec{l} + \int_{\textcircled{3}} \vec{A} \cdot d\vec{l}$$

$$\int_{\textcircled{1}} \vec{A} \cdot d\vec{l} = \int_0^1 (\hat{x}y^3 + \hat{y}x^3) \cdot \hat{x} dx \Big|_{y=0} = \int_0^1 y^3 dx \Big|_{y=0} = 0$$

$$\int_{\textcircled{2}} \vec{A} \cdot d\vec{l} = \int_0^1 (\hat{x}y^3 + \hat{y}x^3) \cdot \hat{y} dy \Big|_{x=1} = \int_0^1 x^3 dy \Big|_{x=1} = \frac{1}{2}$$

$$\int_{\textcircled{3}} \vec{A} \cdot d\vec{l} = \int_0^1 (\hat{x}y^3 + \hat{y}x^3) \cdot (-\hat{x} dx - \hat{y} dy)$$

$$= \int_0^1 -x^3 dy - y^3 dx \Big|_{x=y} = -2 \int_0^1 x^3 dx = -2 \cdot \frac{x^4}{4} \Big|_0^1 = -\frac{1}{2}$$

$$\boxed{\oint \vec{A} \cdot d\vec{l} = -\frac{1}{2} + 1 = \frac{1}{2}}$$

$$\nabla \times \vec{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^3 & x^3 & 0 \end{vmatrix} = \hat{x}(3x^2 - 3y^2)$$

$$\iint (\nabla \times \vec{A}) \cdot d\vec{s} = \int_0^1 dx \int_0^x dy \cdot (3x^2 - 3y^2)$$

$$= \int_0^1 (3x^3 - y^3 \Big|_0^x) dx = \int_0^1 2x^3 dx = 2 \cdot \frac{x^4}{4} \Big|_0^1 = \frac{1}{2}$$

3 (30 points) T is a scalar, and \vec{A} is a vector. Prove in (x, y, z) coordinate that

(a) $\nabla \times (\nabla T) = 0$

(b) $\nabla \cdot (\nabla \times \vec{A}) = 0$

(c) $\nabla \cdot (\nabla T) = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2}$

(a) $\nabla T = \hat{x} \frac{\partial T}{\partial x} + \hat{y} \frac{\partial T}{\partial y} + \hat{z} \frac{\partial T}{\partial z}$

$$\nabla \times (\nabla T) = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial T}{\partial x} & \frac{\partial T}{\partial y} & \frac{\partial T}{\partial z} \end{vmatrix} = \hat{x} \left[\frac{\partial}{\partial y} \left(\frac{\partial T}{\partial z} \right) - \frac{\partial}{\partial z} \left(\frac{\partial T}{\partial y} \right) \right]$$

$$+ \hat{y} \left[\frac{\partial}{\partial z} \left(\frac{\partial T}{\partial x} \right) - \frac{\partial}{\partial x} \left(\frac{\partial T}{\partial z} \right) \right]$$

$$+ \hat{z} \left[\frac{\partial}{\partial x} \left(\frac{\partial T}{\partial y} \right) - \frac{\partial}{\partial y} \left(\frac{\partial T}{\partial x} \right) \right]$$

$$= 0$$

(b) $\nabla \times \vec{A} = \hat{x} \left(\frac{\partial}{\partial y} A_z - \frac{\partial}{\partial z} A_y \right) + \hat{y} \left(\frac{\partial}{\partial z} A_x - \frac{\partial}{\partial x} A_z \right)$

$$+ \hat{z} \left(\frac{\partial}{\partial x} A_y - \frac{\partial}{\partial y} A_x \right)$$

$$\nabla \cdot (\nabla \times \vec{A}) = \frac{\partial}{\partial x} \left[\frac{\partial}{\partial y} A_z - \frac{\partial}{\partial z} A_y \right] + \frac{\partial}{\partial y} \left[\frac{\partial}{\partial z} A_x - \frac{\partial}{\partial x} A_z \right]$$

$$+ \frac{\partial}{\partial z} \left[\frac{\partial}{\partial x} A_y - \frac{\partial}{\partial y} A_x \right]$$

$$= \frac{\partial^2 A_z}{\partial x \partial y} - \frac{\partial^2 A_y}{\partial x \partial z} + \frac{\partial^2 A_x}{\partial y \partial z} - \frac{\partial^2 A_z}{\partial y \partial x} + \frac{\partial^2 A_y}{\partial z \partial x} - \frac{\partial^2 A_x}{\partial z \partial y}$$

Cancel