



Chapter 3

Assembly Language Programming

The 80386, 80486, and Pentium Processors, Triebel
Prof. Yan Luo, UMass Lowell



Introduction

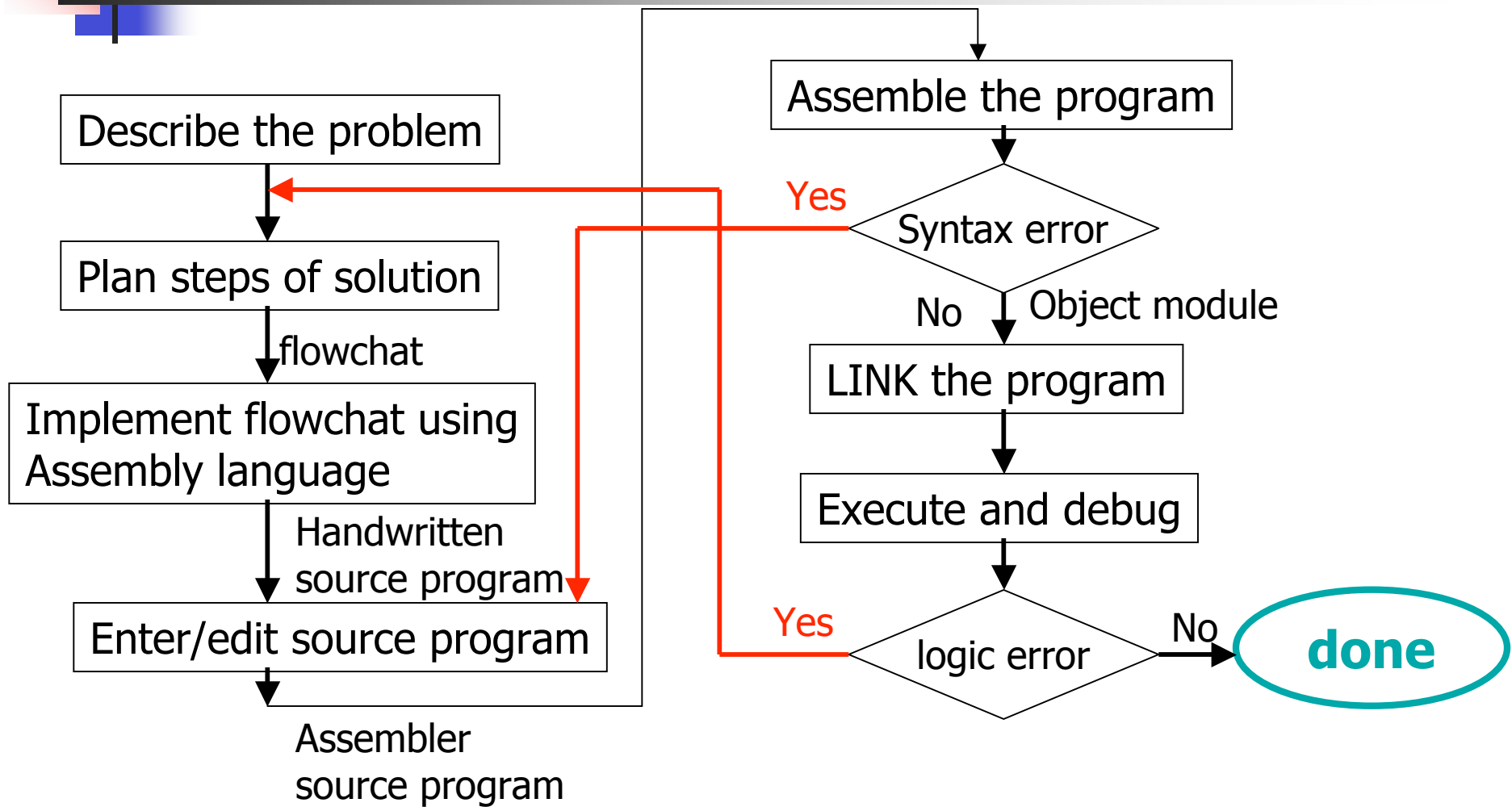
- 3.2 Software: The Microcomputer Program
- 3.3 Assembly Language Program Development on the IBM-Compatible PC/AT
- 3.4 The 80386DX Microprocessor Instruction Set
- 3.5 Addressing Modes of the 80386DX Microprocessor



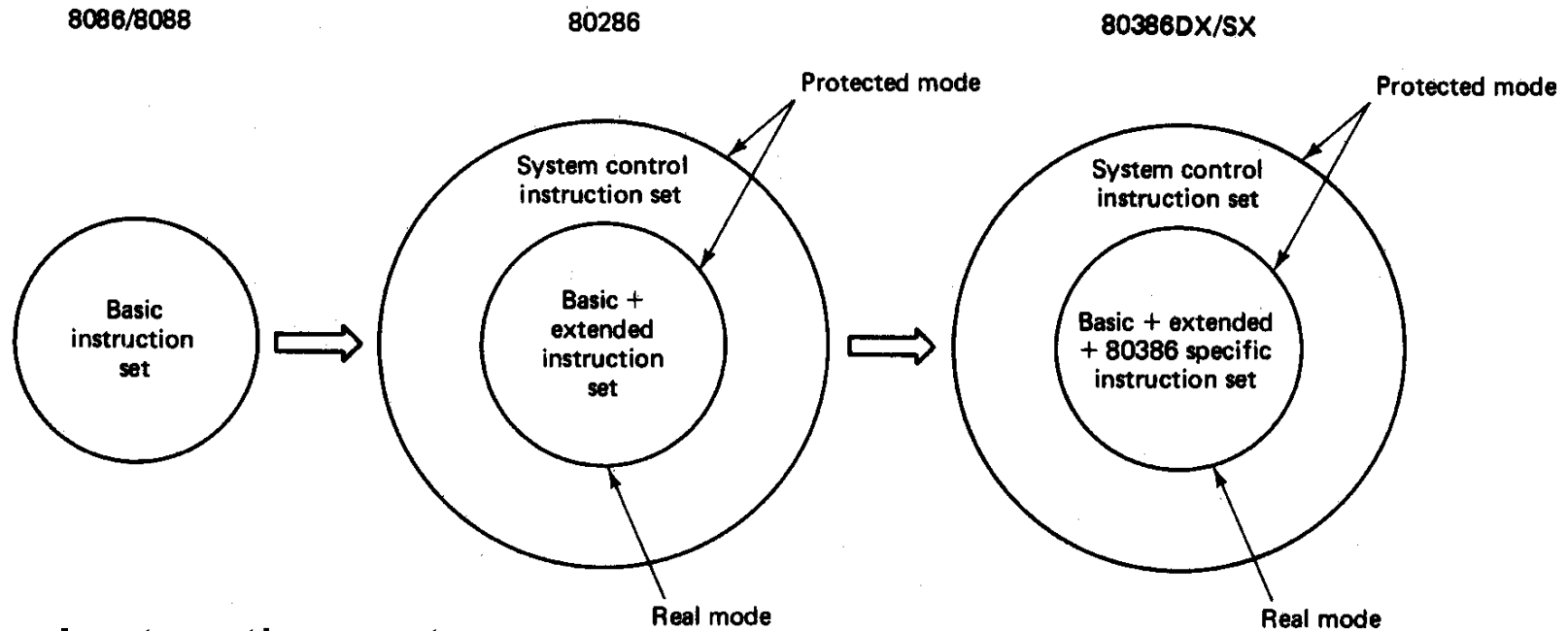
Software

- Instruction -> Program -> Software
- Machine language -> Assembly Language -> High Level Language (C/C++, Java)
- Source code -> Object code -> Executable
- Assembly language
 - Instruction: `Label: Instruction ; comment`
Example: `START: MOV EAX, EBX; COPY EBX INTO EAX`
 - List file: line number, offset, machine language (code), instruction, comments

Assembly Language Program Development



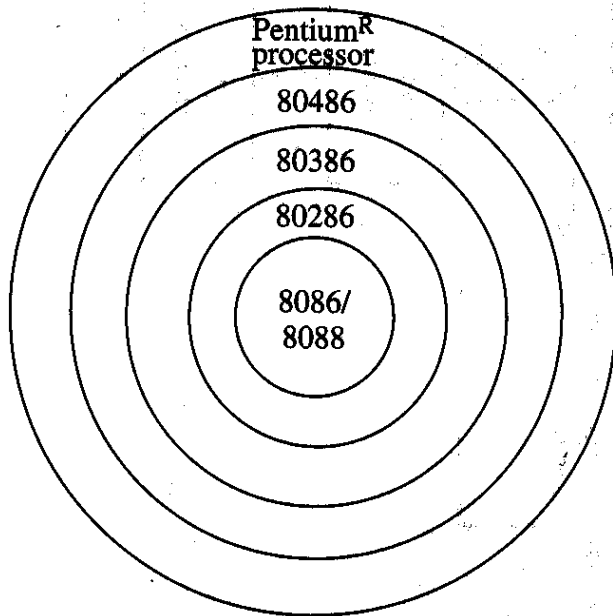
The 80386DX Base Instruction Set



Instruction set

- Defines the basic operations a programmer can make the microprocessor perform
- 8088/8086 instruction set contains 117 basic instructions

Instruction Set Compatibility



- The 80x86 instruction set has evolved in an upward compatible manner
 - Base instruction set → 8088/8086 processor
 - Extended instruction set → 80286 processor
 - System control instruction set → 80286 processor
 - 80386 specific instruction set → 80386DX/SX
 - 80486 specific instruction set → 80486DX/SX
 - Pentium specific instruction set → Original Pentium processor



Instruction Groups

- **Instruction groups**
 - **Instructions are organized into groups of functionally related instructions**
 - **Data Transfer instructions**
 - **Input/output instructions**
 - **Arithmetic instructions**
 - **Logic instructions**
 - **String Instructions**
 - **Control transfer instructions**
 - **Processor control**



Instruction Assembly Notation

- Each instruction is represented by a mnemonic that describes its operation—called its operation code (opcode)
 - MOV = move → data transfer
 - ADD = add → arithmetic
 - AND = logical AND → logic
 - JMP = unconditional jump → control transfer
- Operands are the other parts of an assembly language Instructions
 - Identify whether the elements of data to be processed are in registers or memory
 - Source operand— location of one operand to be process
 - Destination operand—location of the other operand to be processed and the location of the result

Machine Language

DATA TRANSFER

MOV = Move:

	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0
Register / memory to / from register	1 0 0 0 1 0 d w	mod reg r/m	(DISP-LO)	(DISP-HI)		
Immediate to register / memory	1 1 0 0 0 1 1 w	mod 0 0 0 r/m	(DISP-LO)	(DISP-HI)	data	data if w = 1
Immediate to register	1 0 1 1 w reg	data	data if w = 1			
Memory to accumulator	1 0 1 0 0 0 0 w	addr-lo	addr-hi			
Accumulator to memory	1 0 1 0 0 0 1 w	addr-lo	addr-hi			
Register / memory to segment register	1 0 0 0 1 1 1 0	mod 0 SR r/m	(DISP-LO)	(DISP-HI)		
Segment register to register / memory	1 0 0 0 1 1 0 0	mod 0 SR r/m	(DISP-LO)	(DISP-HI)		

- Native language of the 8088/8086 (PC) is machine language (code)
 - One to one correspondence to assembly language statements
 - Instructions encoded with 0's and 1's
 - Machine instructions can take up from 1 to 6 bytes
 - Example: Move=MOV
 - The wide choice of register operands, memory operands, and addressing mode available to access operands in memory expands the move instruction to 28 different forms
 - Ranges in size from 2 to 6 bytes



Software and the Program

- Microcomputer is a general computation resource
 - Has the ability to process data, but does not know how the data is to be processed
 - Must be told:
 - Where to get information (data)?
 - What to do with the information?
 - Where to put the results?
 - This is the job of the program
- Program: sequence of instructions that tells the computer what to do
 - Simple program—few instructions
 - Complex program—100Ks to millions of instructions
 - Microcomputer fetches and executes one instruction after the other
 - Instructions guide the uC step by step through the task that is to be performed



Software and the Program

- System software—a group of programs that enable the microcomputer to operate
 - The operating system (OS)
 - Windows98
 - Windows2000
- Application programs—a collection of programs installed on the microcomputer for use by the operator.
 - Word
 - Excel
 - PowerPoint



Structure of an Assembly Language Statement

- General structure of an assembly language statement

LABEL: INSTRUCTION ; COMMENT

- Label—address identifier for the statement
- Instruction—the operation to be performed
- Comment—documents the purpose of the statement
- Example:

START: MOV AX, BX ; Copy BX into AX

- Other examples:

INC SI ; Update pointer

ADD AX, BX

- Few instructions have a label—usually marks a jump to point
- Not all instructions need a comment



Source Program

```
TITLE   BLOCK-MOVE PROGRAM

PAGE    ,132

COMMENT *This program moves a block of specified number of bytes
        from one place to another place*

;Define constants used in this program

        N      =      16      ;Bytes to be moved
        BLK1ADDR=    100H      ;Source block offset address
        BLK2ADDR=    120H      ;Destination block offset addr
        DATASEGADDR= 1020H     ;Data segment start address

STACK_SEG   SEGMENT          STACK 'STACK'
             DB              64 DUP (?)
STACK_SEG   ENDS

CODE_SEG    SEGMENT          'CODE'
BLOCK       PROC             FAR
            ASSUME CS:CODE_SEG,SS:STACK_SEG

;To return to DEBUG program put return address on the stack

            PUSH    DS
            MOV     AX, 0
            PUSH    AX

;Set up the data segment address

            MOV     AX, DATASEGADDR
            MOV     DS, AX

;Set up the source and destination offset addresses

            MOV     SI, BLK1ADDR
            MOV     DI, BLK2ADDR

;Set up the count of bytes to be moved

            MOV     CX, N

;Copy source block to destination block

NXTPT:     MOV     AH, [SI]      ;Move a byte
            MOV     [DI], AH
            INC     SI          ;Update pointers
            INC     DI
            DEC     CX          ;Update byte counter
            JNZ    NXTPT       ;Repeat for next byte
            RET                ;Return to DEBUG program

BLOCK      ENDP
CODE_SEG   ENDS
END        BLOCK                ;End of program
```



Assembler and the source program

- Assembly language program
 - Assembly language program (.asm) file—known as source code
 - Converted to machine code by a process called assembling
 - Assembling performed by a software program—an 80x86 assembler
 - Machine (object) code that can be run is output in the executable (.exe) file
 - Source listing output in (.lst) file—printed and used during execution and debugging of program
- DEBUG—part of disk operating system (DOS) of the PC
 - Permits programs to be assembled and disassembled
 - Line-by-line assembler
 - Also permits program to be run and tested

The Listing File

Microsoft (R) Macro Assembler Version 5.10
BLOCK-MOVE PROGRAM

5/17/92 18:10:04
Page 1-1

```
1
2
3
4
5
6
7
8
9
10
11
12
13 = 0010
14 = 0100
15 = 0120
16 = 1020
17
18
19 0000
20 0000 0040[
21    ??
22    ]
23
24 0040
25
26
27 0000
28 0000
29
30
31
32
33 0000 1E
34 0001 B8 0000
35 0004 50
36
37
38
39 0005 B8 1020
40 0008 8E D8
41
42
43
44 000A BE 0100
45 000D BF 0120
46
47
48
49 0010 B9 0010
50
51
52
53 0013 8A 24
54 0015 88 25
55 0017 46
56 0018 47
57 0019 49
58 001A 75 F7
59 001C CB
60 001D
61 001D
62
```

```
TITLE BLOCK-MOVE PROGRAM

PAGE          ,132
COMMENT *This program moves a block of specified number of bytes
        from one place to another place*

;Define constants used in this program
N=          16          ;Bytes to be moved
BLK1ADDR=   100H       ;Source block offset address
BLK2ADDR=   120H       ;Destination block offset addr
DATASEGADDR=1020H     ;Data segment start address

STACK_SEG   SEGMENT   STACK 'STACK'
            DB        64 DUP(?)

STACK_SEG   ENDS

CODE_SEG    SEGMENT   'CODE'
BLOCK      PROC      FAR
ASSUME     CS:CODE_SEG,SS:STACK_SEG

;To return to DEBUG program put return address on the stack
PUSH DS
MOV AX, 0
PUSH AX

;Setup the data segment address
MOV AX, DATASEGADDR
MOV DS, AX

;Setup the source and destination offset addresses
MOV SI, BLK1ADDR
MOV DI, BLK2ADDR

;Setup the count of bytes to be moved
MOV CX, N

;Copy source block to destination block
NXTPT:MOV AH, [SI]          ;Move a byte
MOV [DI], AH
INC SI                      ;Update pointers
INC DI
DEC CX                      ;Update byte counter
JNZ NXTPT                  ;Repeat for next byte
RET                          ;Return to DEBUG program

BLOCK      ENDP
CODE_SEG  ENDS
END        BLOCK           ;End of program
```



The Listing File

Instruction statements—operations to be performed by the program

- **Example—line 53**

```
0013 8A 24 NXTPT: MOV AH, [SI] ;Move a byte
```

Where:

0013 = offset address of first byte of code in the current CS

8A24 = machine code of the instruction

NXTPT: = Label

MOV = instruction mnemonic

AH = destination operand—a register

[SI] = source operand—in memory

;Move xxxxx = comment

- **Directives—provides directions to the assembler program**

- **Example—line 20**

```
0000 0040 DB 64 DUP(?)
```

Defines and leaves un-initialized a block of 64 bytes in memory for the stack

More Information in the Listing

- Other information provided in the listing
 - Size of code segment and stack
 - Names, types, and values of constants and variables
 - # lines and symbols used in the program
 - # errors that occurred during assembly

```
Segments and Groups:
Name          Length  Align  Combine Class
CODE_SEG     001D  PARA  NONE   'CODE'
STACK_SEG    0040  PARA  STACK  'STACK'

Symbols:
Name          Type      Value      Attr
BLK1ADDR     NUMBER    0100
BLK2ADDR     NUMBER    0120
BLOCK        F PROC    0000  CODE_SEG  Length = 001D
DATASEGADDR  NUMBER    1020
NEXTPT       L NEAR    0013  CODE_SEG

@CPU         TEXT     0101h
@FILENAME    TEXT     block
@VERSION     TEXT     510

59 Source Lines
59 Total Lines
15 Symbols

47222 + 347542 Bytes symbol space free

0 Warning Errors
0 Severe Errors

(b)
```



Addressing Modes

- Instructions perform the operation they specify on elements of data that are called its operand
- Types of operands
 - Source operand
 - Destination operand
 - Content of source operand combined with content of destination operand → Result saved in destination operand location
- Operands may be
 - Part of the instruction—source operand only
 - Held in one of the internal registers—both source and destination operands
 - Stored at an address in memory—either the source or destination operand
 - Held in an input/output port—either the source or destination operand



Addressing Modes

- Types of addressing modes
 - Register addressing modes
 - Immediate operand addressing
 - Memory operand addressing
- Each operand can use a different addressing mode

Register Operand Addressing Mode

- Register addressing mode operands

- Source operand and destination operands are both held in internal registers of the 80386DX/SX

- Only the data registers can be accessed as bytes, words, or double words

Ex. AL,AH → bytes

AX → word

EAX → double word

- Index and pointer registers as words or double words

Ex. SI → word pointer

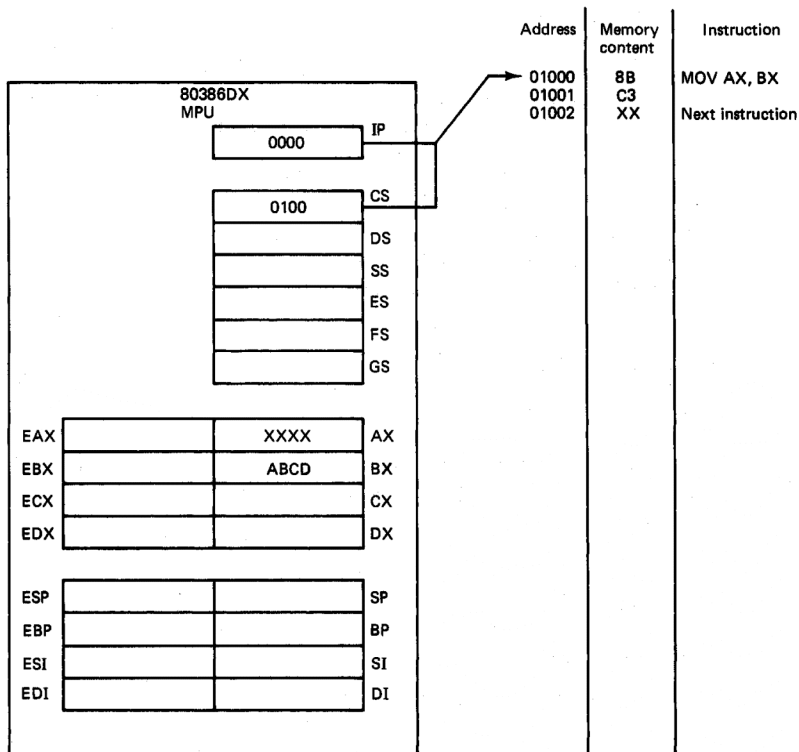
ESI → double word pointer

- Segment registers only as words

Ex. DS → word pointer

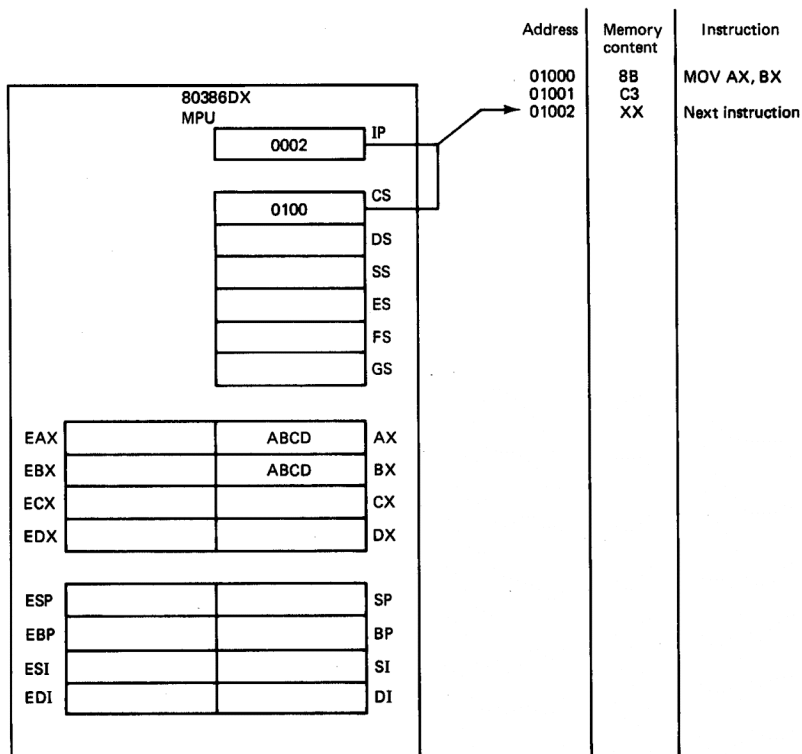
Register	Operand size		
	Byte (Reg8)	Word (Reg16)	Double word (Reg32)
Accumulator	AL, AH	AX	EAX
Base	BL, BH	BX	EBX
Count	CL, CH	CX	ECX
Data	DL, DH	DX	EDX
Stack pointer	—	SP	ESP
Base pointer	—	BP	EBP
Source index	—	SI	ESI
Destination index	—	DI	EDI
Code segment	—	CS	—
Data segment	—	DS	—
Stack segment	—	SS	—
E data segment	—	ES	—
F data segment	—	FS	—
G data segment	—	GS	—

Register Operand Addressing Mode



- Example
MOV AX,BX
Source = BX → word data
Destination = AX → word data
Operation: (BX) → (AX)
- State before fetch and execution
CS:IP = 0100:0000 = 01000H
Move instruction code = 8BC3H
(01000H) = 8BH
(01001H) = C3H
(BX) = ABCDH
(AX) = XXXX → don't care state

Register Operand Addressing Mode



- Example (continued)

- State after execution

$CS:IP = 0100:0002 = 01002H$

$01002H \rightarrow$ points to next sequential instruction

$(BX) = ABCDH$

$(AX) = ABCDH \rightarrow$ Value in BX copied into AX

Rest of the bits in EAX unaffected

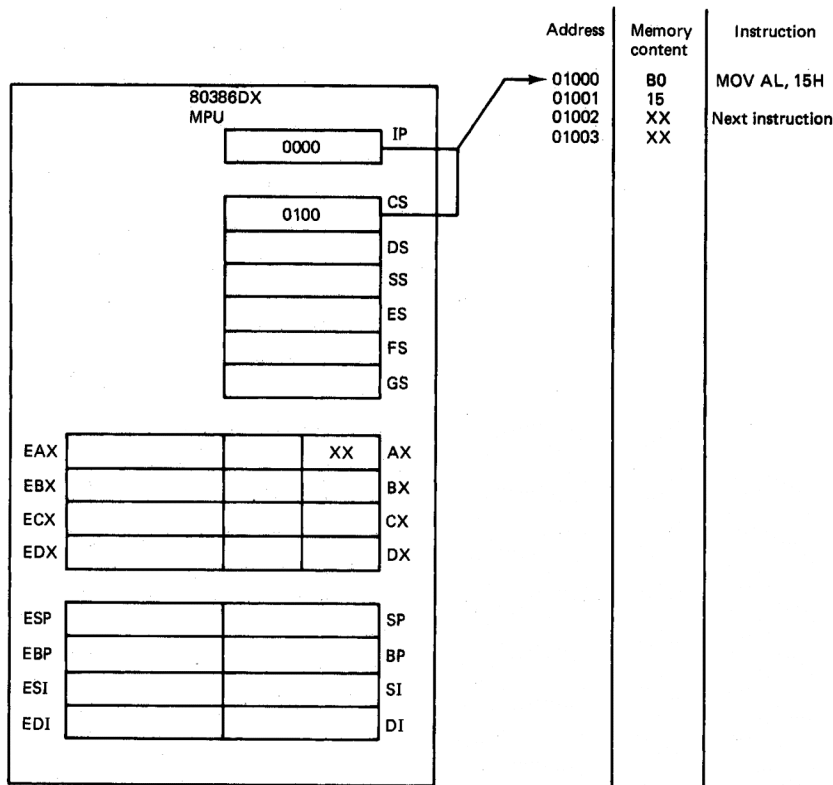


Immediate Operand Addressing Mode



- Immediate operand
 - Operand is coded as part of the instruction
 - Applies only to the source operand
 - Destination operand uses register addressing mode or a memory addressing mode
- Types
 - Imm8 = 8-bit immediate operand
 - Imm16 = 16-bit immediate operand
 - Imm32 = 32-bit immediate operand
- General instruction structure and operation
 - MOV Rx,ImmX
 - ImmX → (Rx)

Immediate Operand Addressing Mode



- Example**

MOV AL, 15H

Source = Imm8 → immediate byte data

Destination = AL → Byte of data

Operation: (Imm8) → (AL)
- State before fetch and execution**

CS:IP = 0100:0000 = 01000H

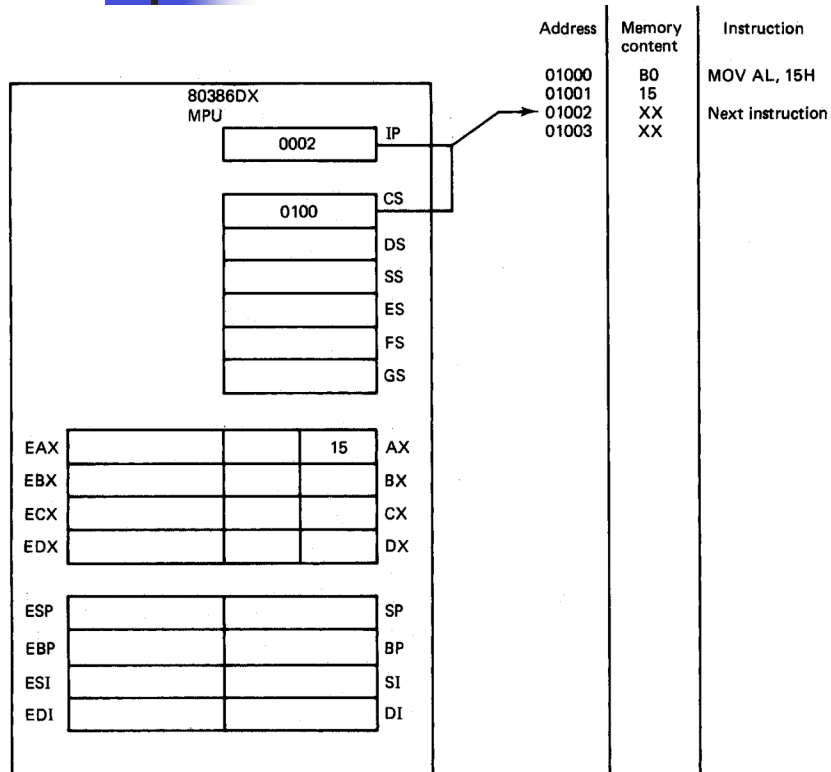
Move instruction code = B015H

(01000H) = B0H

(01001H) = 15H → Immediate data

(AL) = XX → don't care state

Immediate Operand Addressing Mode



- Example (continued)

- State after execution

CS:IP = 0100:0002 = 01002H

01002H → points to next sequential instruction

(AL) = 15H → Immediate value in copied into AX

Rest of bits in EAX unaffected



16-bit Memory Operand Addressing Modes

PA = SBA : EA

PA = Segment base : Base + Index + Displacement

$$PA = \left\{ \begin{array}{c} CS \\ SS \\ DS \\ ES \end{array} \right\} : \left\{ \begin{array}{c} BX \\ BP \end{array} \right\} + \left\{ \begin{array}{c} SI \\ DI \end{array} \right\} + \left\{ \begin{array}{c} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{array} \right\}$$

- Accessing operands in memory
 - Only one operand can reside in memory—either the source or destination
 - Calculate the 20-bit physical address (PA) at which the operand is stored in memory
 - Perform a read or write to this memory location
 - 16-bit memory addressing modes produce 8088/8086/80286 compatible code

16-bit Memory Operand Addressing Modes

- Physical address computation

- Given in general as

$$PA = SBA:EA$$

SBA = Segment base address

EA = Effective address

- Components of a effective address

- Base → base registers BX or BP
- Index → index register SI or DI
- Displacement → 8 or 16-bit displacement
- Not all elements are used in all computations—results in a variety of addressing modes

$$PA = SBA : EA$$

$$PA = \text{Segment base} : \text{Base} + \text{Index} + \text{Displacement}$$

$$PA = \left\{ \begin{array}{c} CS \\ SS \\ DS \\ ES \end{array} \right\} : \left\{ \begin{array}{c} BX \\ BP \end{array} \right\} + \left\{ \begin{array}{c} SI \\ DI \end{array} \right\} + \left\{ \begin{array}{c} \text{8-bit displacement} \\ \text{16-bit displacement} \end{array} \right\}$$

Direct Addressing Mode

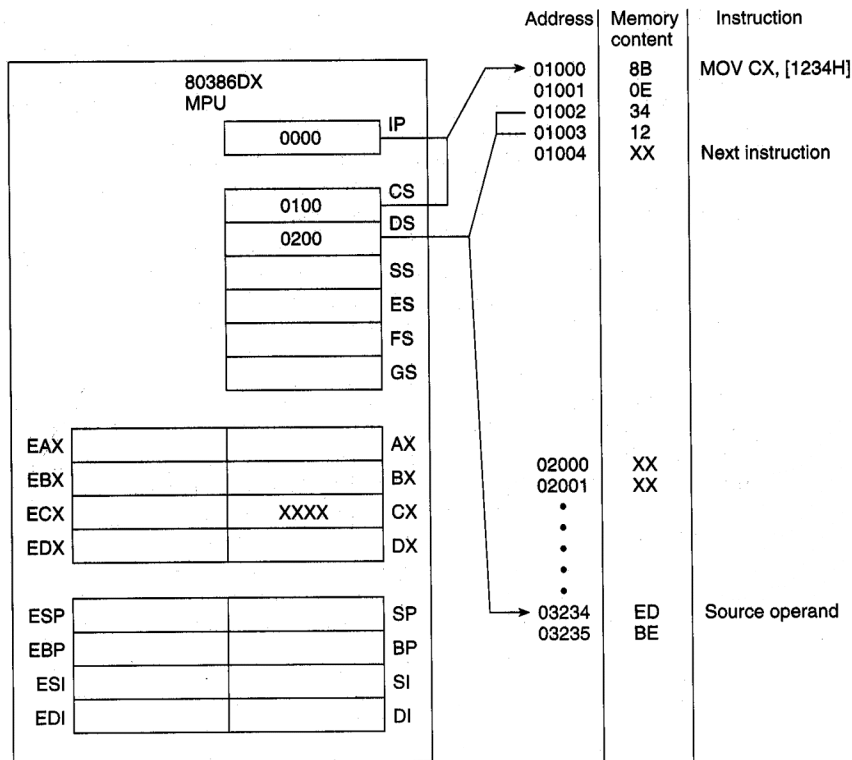
PA = Segment base:Direct address

$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \{ \text{Direct address} \}$$

- Direct addressing mode
 - Similar to immediate addressing in that information coded directly into the instruction
 - Immediate information is the effective address—called the direct address
- Physical address computation
 - PA = SBA:EA → 20-bit address
 - PA = SBA:[DA] → immediate 8-bit or 16 bit displacement
 - Segment base address is DS by default
PA = DS:[DA]
 - Segment override prefix (SEG) is required to enable use of another segment register
PA = ES:[DA]

Direct Addressing Mode (Example: MOV CX, [1234H])

- State before fetch and execution



- Instruction

CS = 0100H

IP = 0000H

CS:IP = 0100:0000H = 01000H

(01000H,01001H) = Opcode = 8B0E

(01003H,01002) = DA = 1234H

- Source operand—direct address

DS = 0200H

DA = 1234H

PA = DS:DA = 0200H:1234H

= 02000H + 1234H

= 03234H

(03235H,03234H) = BEEDH

- Destination operand—register operand addressing

(CX) = XXXX → don't care state

Direct Addressing Mode (Example: MOV CX, [1234H])

- Example (continued)
- State after execution

- Instruction

CS:IP = 0100:0004 = 01004H

01004H → points to next sequential instruction

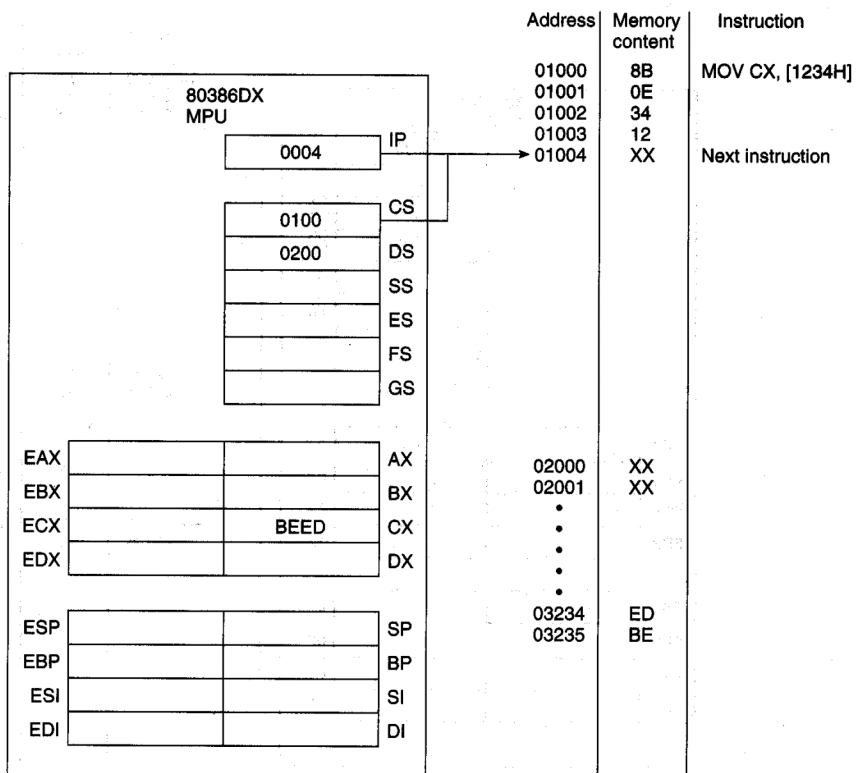
- Source operand

(03235H,03234H) = BEEDH → unchanged

- Destination operand

(CX) = BEED

Rest of bits in ECX unaffected



Register Indirect Addressing Mode

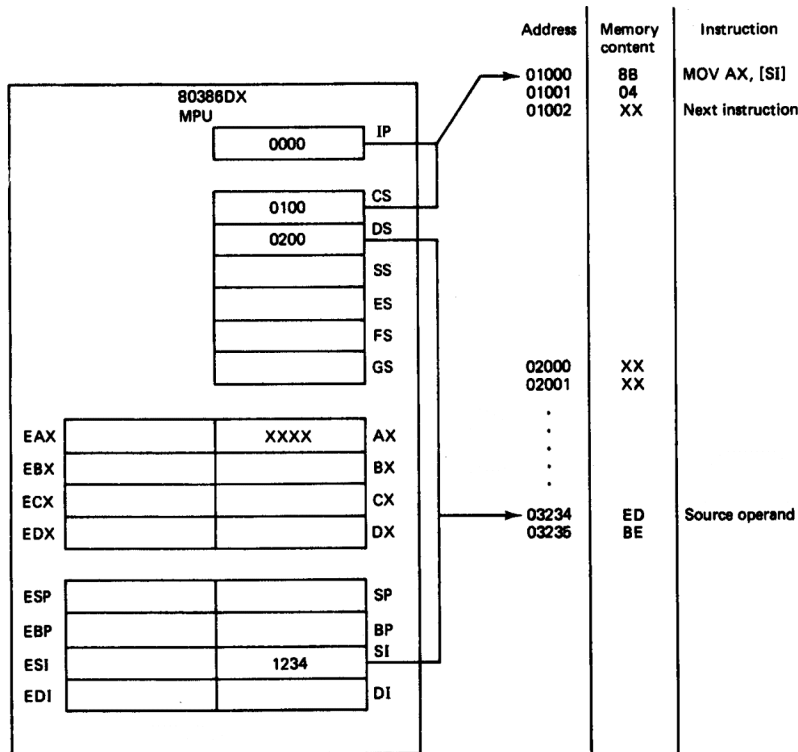
PA = Segment base: Indirect address

$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \left\{ \begin{array}{c} BX \\ BP \\ SI \\ DI \end{array} \right\}$$

- Register indirect addressing mode
 - Similar to direct addressing in that the effective address is combined with the contents of DS to obtain the physical address
 - Effective address resides in either a base or index register
- Physical address computation
 - PA = SBA:EA → 20-bit address
 - PA = SBA:[Rx] → 16-bit offset
 - Segment base address is DS by default
 - PA = DS:[Rx]
 - Segment override prefix (SEG) is required to enable use of another segment register
 - PA = ES:[Rx]

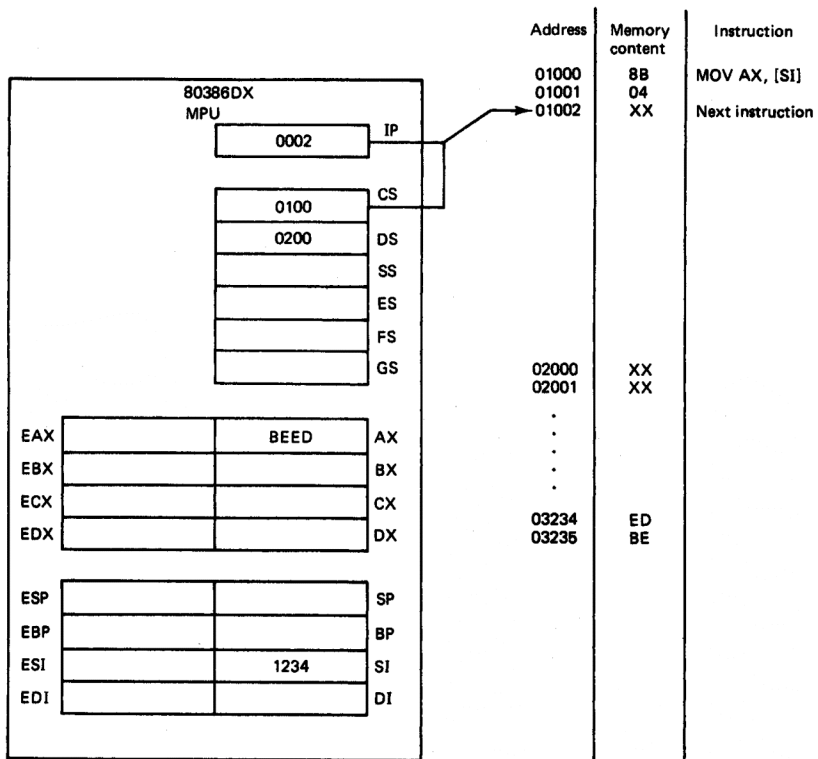
Register Indirect Addressing Mode (example: MOV AX, [SI])

- State before fetch and execution



- Instruction
 - CS = 0100H, IP = 0000H
 - CS:IP = 0100:0000H = 01000H
 - (01000H,01001H) = Opcode = 8B04H
 - Source operand—register indirect addressing
 - DS = 0200H, SI = 1234H
 - PA = DS:SI = 0200H:1234H
 - = 02000H + 1234H = 03234H
 - (03235H,03234H) = BEEDH
 - Destination operand—register operand addressing
 - (AX) = XXXX → don't care state

Register Indirect Addressing Mode (example: MOV AX, [SI])



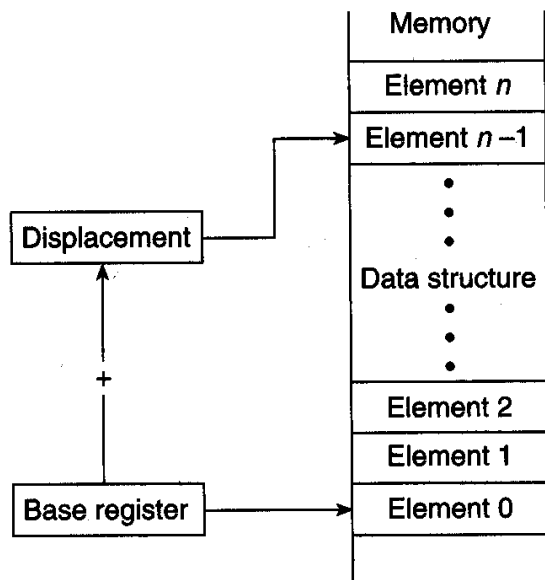
- Example (continued)
- State after execution

- Instruction
 - CS:IP = 0100:0002 = 01002H
 - 01002H → points to next sequential instruction
- Source operand
 - (03235H,03234H) = BEEDH → unchanged
- Destination operand
 - (AX) = BEED
 - Rest of bits in EAX unaffected

Base Addressing Mode

$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \left\{ \begin{array}{c} BX \\ BP \end{array} \right\} + \left\{ \begin{array}{c} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{array} \right\}$$

(a)



(b)

Based addressing mode

- Effective address formed from contents of a base register and a displacement
 - Base register is either BX or BP (stack)
 - Direct/indirect displacement is 8-bit or 16bit
- Physical address computation
 - PA = SBA:EA → 20-bit address
 - PA = SBA:[BX or BP] + DA
- Accessing a data structure
 - Based addressing makes it easy to access elements of data in an array
 - Address in base register points to start of the array
 - Displacement selects the element within the array
 - Value of the displacement is simply changed to access another element in the array
 - Program changes value in base register to select another array

Base Addressing Mode (Example: MOV [BX] + 1234H, AL)

Instruction

CS = 0100H, IP = 0000H

CS:IP = 0100:0000H = 01000H

(01000H,01001H) = Opcode = 8807H

(01003H,01002H) = displacement = 1234H

Destination operand—based addressing

DS = 0200H, BX = 1000H

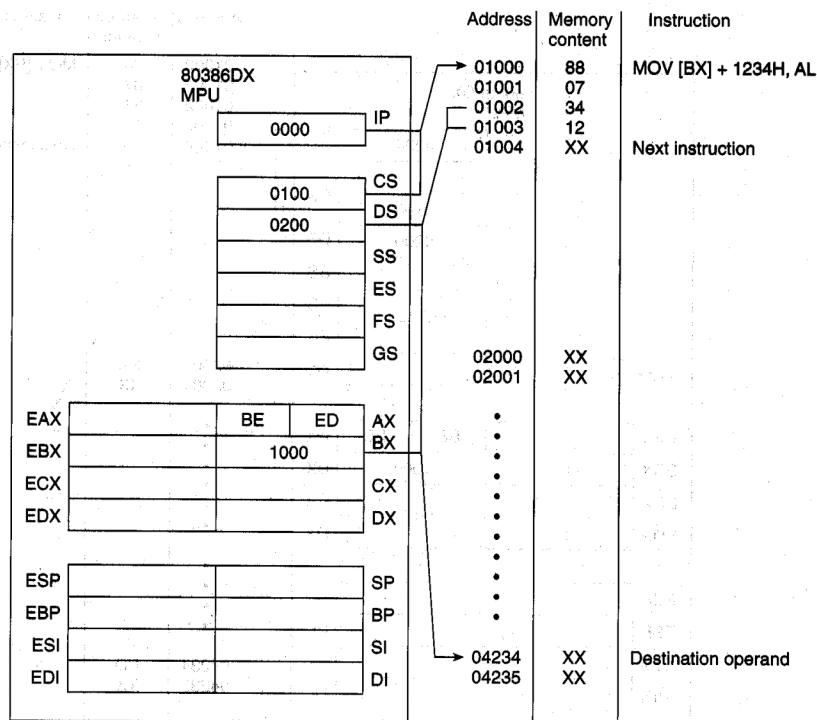
DA = 1234H

PA = DS:BX+DA = 0200H:1000H+1234H
 = 02000H+1000H+1234H
 = 04234H

(04234H) = XXH

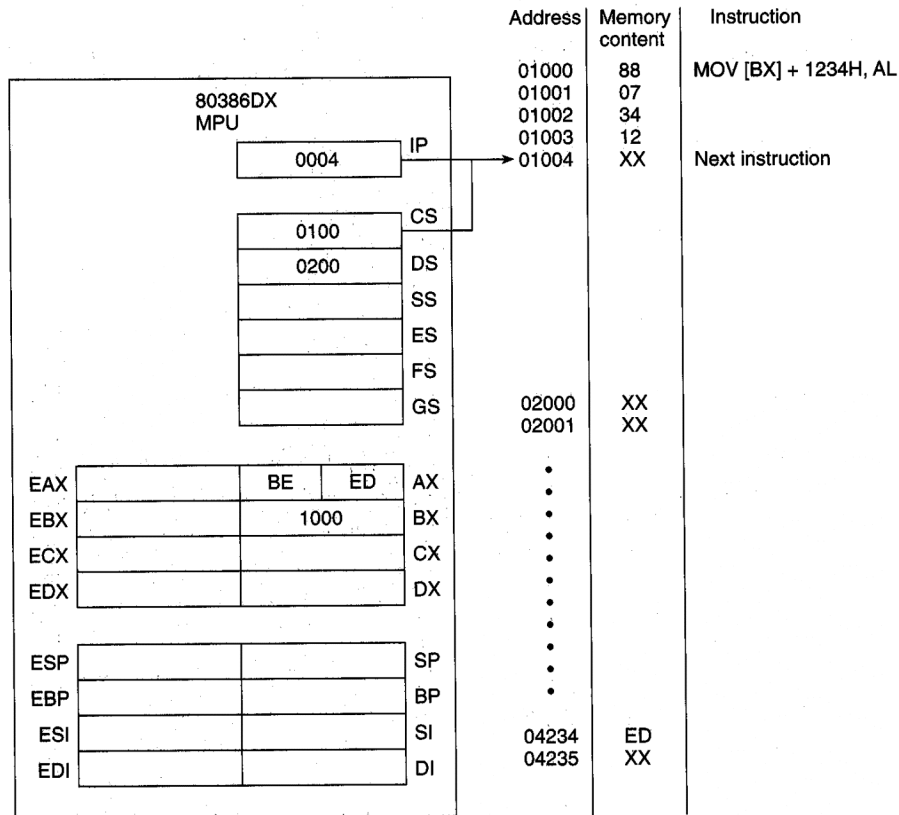
Source operand—register operand addressing

(AL) = ED



Base Addressing Mode

(Example: MOV [BX] + 1234H, AL)



- State after execution

- Instruction

CS:IP = 0100:0004 = 01004H

01004H → points to next sequential instruction

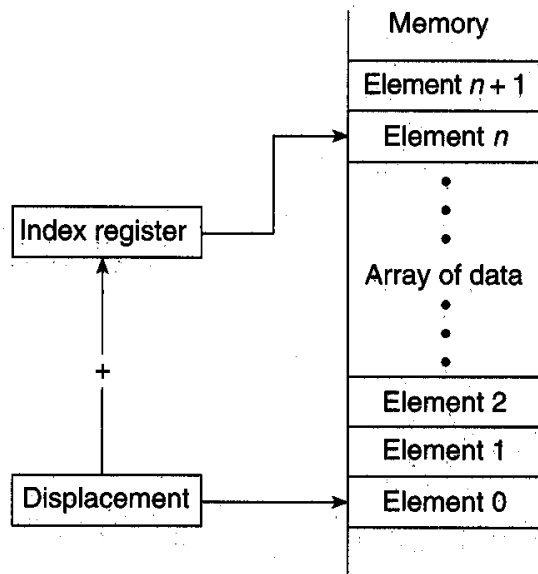
- Destination operand

(04234H) = EDH

- Source operand

(AL) = EDH → unchanged

Indexed Addressing Mode



(a)

PA = Segment base: index + displacement

$$PA = \begin{Bmatrix} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{Bmatrix} : \begin{Bmatrix} SI \\ DI \end{Bmatrix} + \begin{Bmatrix} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{Bmatrix}$$

(b)

Indexed addressing mode

- Similar to based addressing, it makes accessing elements of data in an array easy
- Displacement points to the beginning of array in memory
- Index register selects element in the array
- Program simply changes the value of the displacement to access another array
- Program changes (recomputes) value in index register to select another element in the array

Effective address formed from direct displacement and contents of an index register

- Direct displacement is 8-bit or 16-bit
- Index register is either SI → source operand or DI → destination operand

Physical address computation

PA = SBA:EA → 20-bit address

PA = SBA: DA + [SI or DI]

Indexed Addressing Mode

(Example: MOV AL,[SI] +1234H)

- State before fetch and execution

- Instruction

CS = 0100H, IP = 0000H

CS:IP = 0100:0000H = 01000H

(01000H,01001H) = Opcode = 8A44H

(01003H,01002H) = Direct displacement = 1234H

- Source operand—indexed addressing

DS = 0200H, SI = 2000H, DA = 1234H

PA = DS:SI+DA = 0200H:2000H+1234H

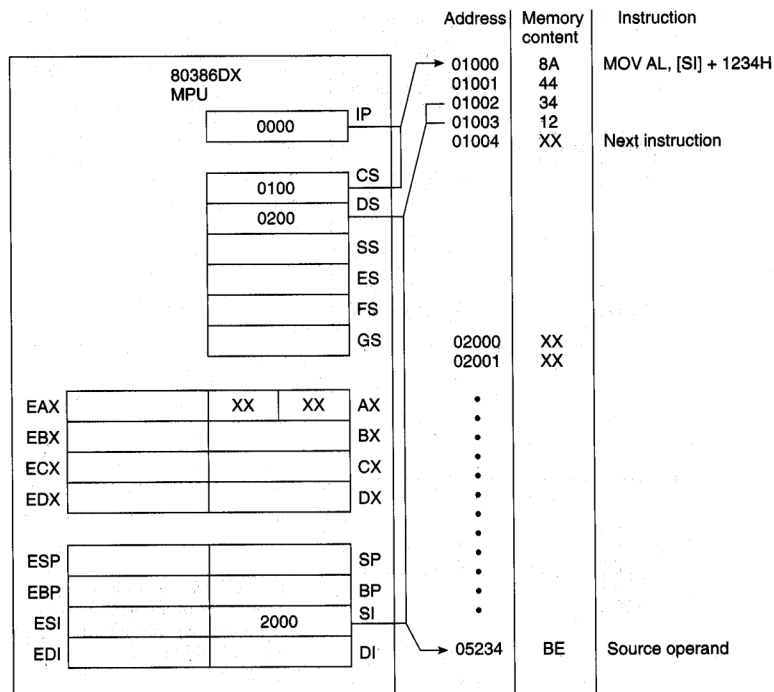
= 02000H+2000H+1234H

= 05234H

(05234H) = BEH

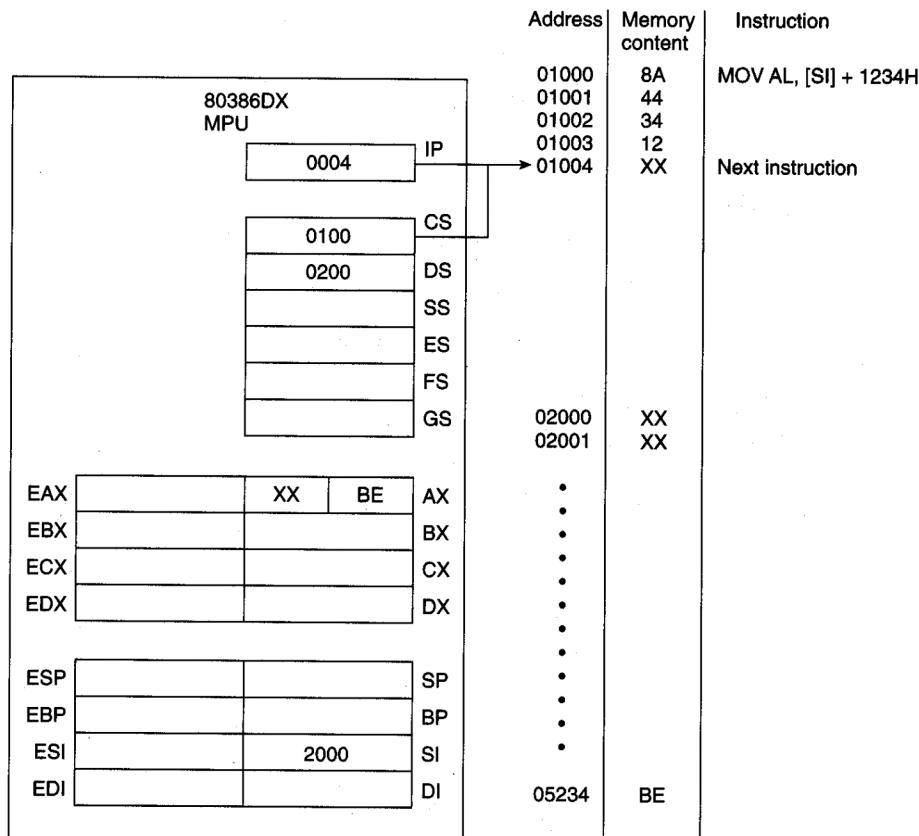
- Destination operand—register operand addressing

(AL) = XX → don't care state



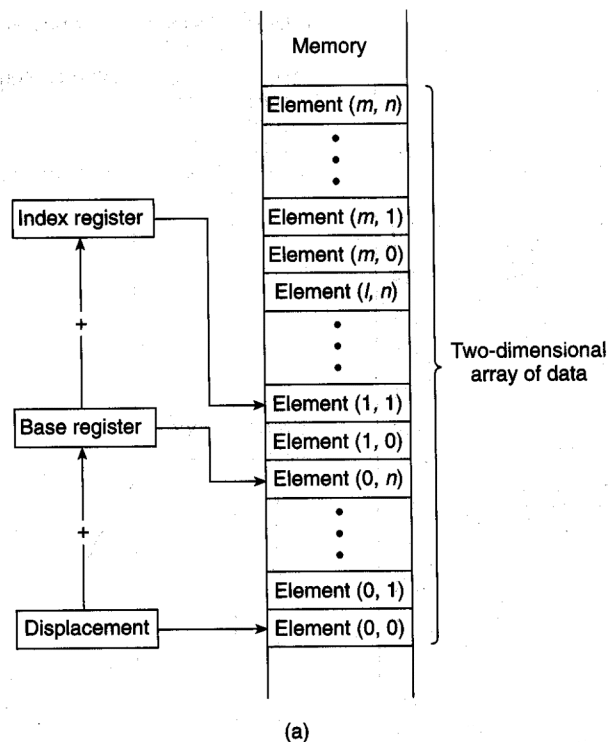
Indexed Addressing Mode

(Example: MOV AL,[SI] +1234H)



- Example (continued)
- State after execution
 - Instruction
 - CS:IP = 0100:0004 = 01004H
 - 01004H → points to next sequential instruction
 - Source operand
 - (05234H) = BEH → unchanged
 - Destination operand
 - (AL) = BEH
 - Rest of bits in EAX unaffected

Based-Indexed Addressing Mode



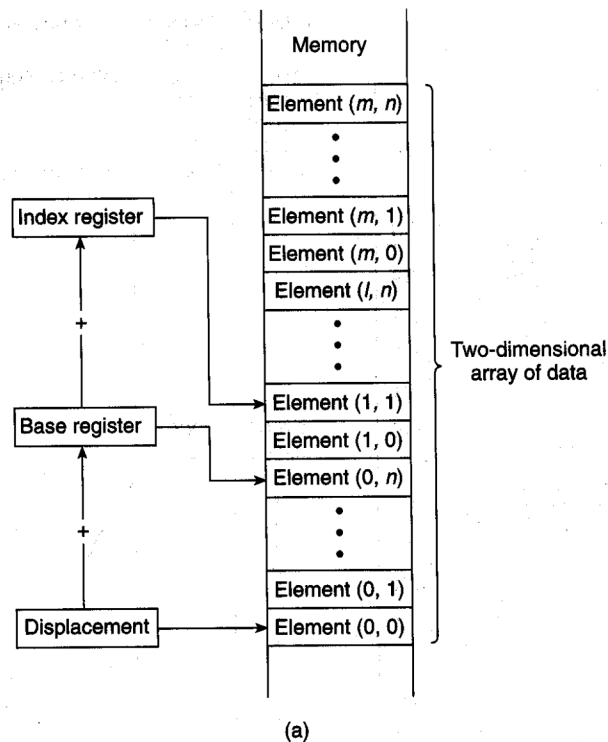
PA = Segment base: base + index + displacement

$$PA = \begin{Bmatrix} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{Bmatrix} : \left\{ \begin{matrix} BX \\ BP \end{matrix} \right\} + \left\{ \begin{matrix} SI \\ DI \end{matrix} \right\} + \left\{ \begin{matrix} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{matrix} \right\}$$

(b)

- Combines the functions of based and indexed addressing modes
- Enables easy access to two-dimensional arrays of data
- Displacement points to the beginning of array in memory
- Base register selects a row (m) of elements
- Index register selects an element in column (n)
- Program simply changes the value of the displacement to access another array
- Program changes (recomputes) value in base register to select another row of elements
- Program changes (recomputes) the value of the index register to select the element in another column

Based-Indexed Addressing Mode



- Effective address formed from direct displacement and contents of a base register and an index register
 - Direct displacement is 8-bit or 16bit
 - Base register either BX or BP (stack)
 - Index register is either SI → source operand or DI → destination operand
- Physical address computation
 - $PA = SBA:EA \rightarrow 20\text{-bit address}$
 - $PA = SBA:DA + [BX \text{ or } BP] + [SI \text{ or } DI]$

PA = Segment base: base + index + displacement

$$PA = \begin{Bmatrix} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{Bmatrix} : \begin{Bmatrix} BX \\ BP \end{Bmatrix} + \begin{Bmatrix} SI \\ DI \end{Bmatrix} + \begin{Bmatrix} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{Bmatrix}$$

(b)

Based- Indexed Addressing Mode Example(MOV AH,[BX][SI] +1234H)

- State before fetch and execution

- Instruction

CS = 0100H, IP = 0000H

CS:IP = 0100:0000H = 01000H

(01000H,01001H) = Opcode = 8A20H

(01003H,01002H) = Direct displacement = 1234H

- Source operand—based-indexed addressing

DA = 1234H,DS = 0200H,BX = 1000H

SI = 2000H

PA = DS:DA +BX +SI

= 0200H:1234H + 1000H + 2000H

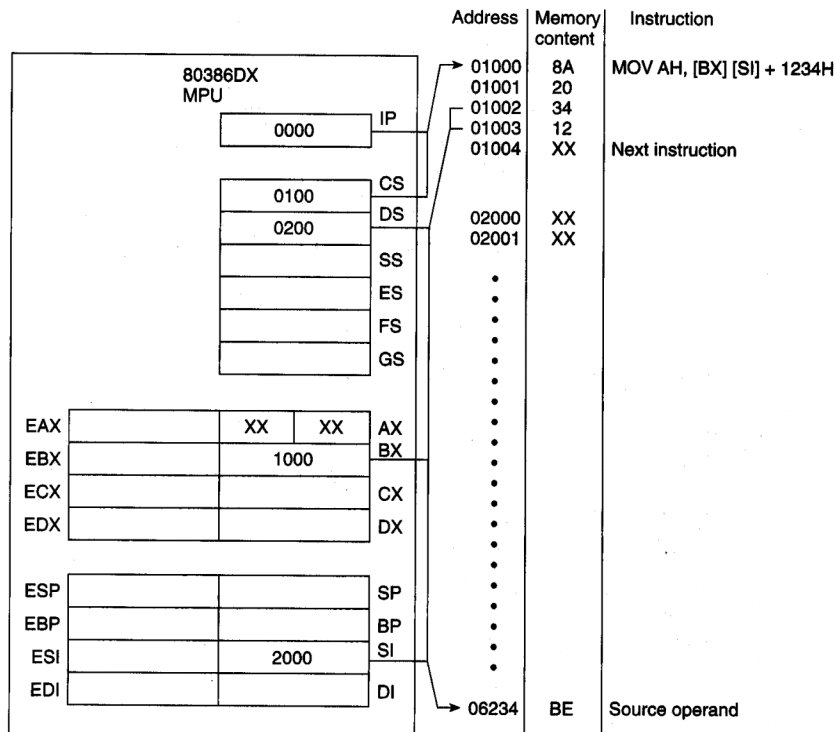
= 02000H+1234H +1000H + 2000H

= 06234H

(06234H) = BEH

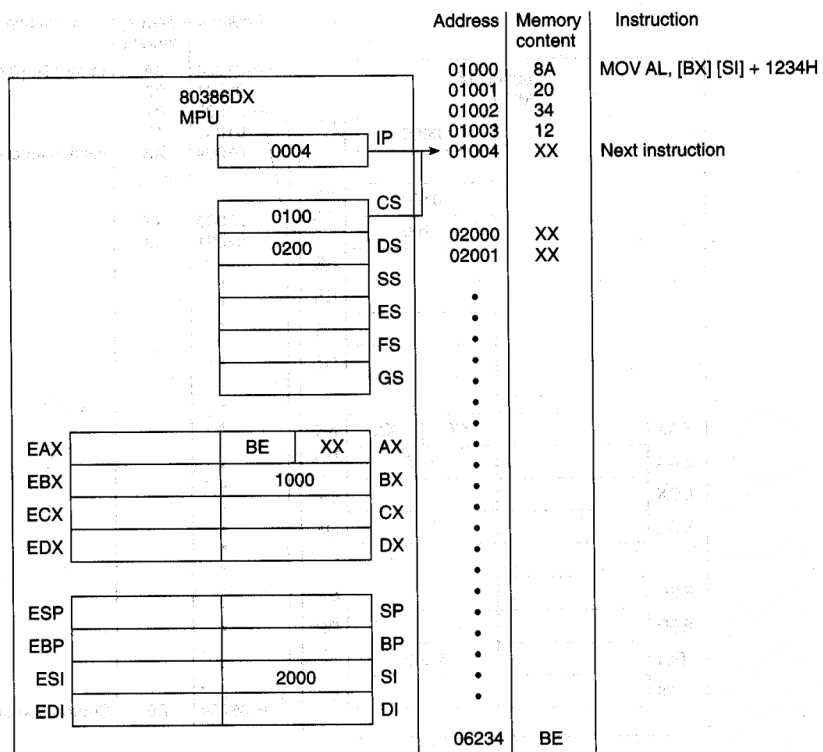
- Destination operand—register operand addressing

(AH) = XX → don't care state



Based- Indexed Addressing Mode

Example(MOV AH,[BX][SI] +1234H)



- Example (continued)
- State after execution
 - Instruction
 - CS:IP = 0100:0004 = 01004H
 - 01004H → points to next sequential instruction
 - Source operand (06234H) = BEH → unchanged
 - Destination operand (AH) = BEH
 - Rest of bits in EAX unaffected

32-bit Memory Operand Addressing Modes

$$PA = \text{Segment base: } \left\{ \text{Base} + (\text{Index} \times \text{Scale factor}) + \text{Displacement} \right\}$$

$$PA = \left\{ \begin{array}{c} \text{CS} \\ \text{SS} \\ \text{DS} \\ \text{ES} \\ \text{FS} \\ \text{GS} \end{array} \right\} : \left\{ \begin{array}{c} \text{AX} \\ \text{BX} \\ \text{CX} \\ \text{DX} \\ \text{SP} \\ \text{BP} \\ \text{SI} \\ \text{DI} \end{array} \right\} + \left\{ \begin{array}{c} \text{AX} \\ \text{BX} \\ \text{CX} \\ \text{DX} \\ \text{BP} \\ \text{SI} \\ \text{DI} \end{array} \right\} \times \left\{ \begin{array}{c} 1 \\ 2 \\ 4 \\ 8 \end{array} \right\} + \left\{ \begin{array}{c} \text{8-bit displacement} \\ \text{16-bit displacement} \end{array} \right\}$$

- Enhanced over the 16 bit memory addressing
- Calculate the 20-bit physical address (PA) at which the operand is stored in memory
- Effective address computation changed
 - Generalized the selection of the register used for the base and index elements
 - Include a fourth element—scale factor
 - Scale factor multiplies the index component
 - Allowed scale factor values are 1,2,4, or 8
- Use of 32-bit memory addressing modes produce code that is not compatible with the 8088/8086/80286

32-bit Memory Operand Addressing Modes

PA = Segment base: Indirect address

$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \left\{ \begin{array}{c} AX \\ BX \\ CX \\ DX \\ SP \\ BP \\ SI \\ DI \end{array} \right\}$$

(a)

PA = Segment base: Base + Displacement

$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \left\{ \begin{array}{c} AX \\ BX \\ CX \\ DX \\ SP \\ BP \\ SI \\ DI \end{array} \right\} + \left\{ \begin{array}{l} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{array} \right\}$$

(b)

PA = Segment base: (Index × Scale factor) + Displacement

$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \left\{ \begin{array}{cc} AX & 1 \\ BX & 1 \\ CX & 1 \\ DX & 2 \\ BP & 4 \\ SI & 4 \\ DI & 8 \end{array} \right\} \times \left\{ \begin{array}{l} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{array} \right\}$$

(c)

PA = Segment base: Base + (Index × Scale factor) + Displacement

$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \left\{ \begin{array}{cc} AX & 1 \\ BX & 1 \\ CX & 1 \\ DX & 2 \\ SP & 4 \\ BP & 4 \\ SI & 8 \\ DI & 8 \end{array} \right\} + \left\{ \begin{array}{l} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{array} \right\}$$

(d)

- Examples:

#1 MOV [AX], BX → destination operand uses AX for indirect address

#2 MOV BL,[AX] +1234H → source operand uses AX for base address component

#3 MOV AL,1234H +[SI X 2]; where: DS =0200H, SI =2000H

$$PA = DS(0)+1234H+(SI \times 2) = 02000H+1234H+(2000H \times 2) = 07234H$$