$$= T_f(x^{g(k)}) + T_f(x^{g(\infty)}) \quad \text{(since } T_f \text{ is linear)}$$
$$= (x^{f(g(k))} + x^{f(\infty)}) + (x^{f(g(\infty))} + x^{f(\infty)})$$
$$= x^{f(g(k))} + x^{f(g(\infty))} \quad \text{(since } u + u = 0 \text{ for all } u \in \mathbb{F}_8)$$
$$= T_{f \circ g}(x^k).$$

- 3. *Proof that T is a homomorphism mapping into* $GL(\mathbb{F}_8)$. We have seen that each element of SLF(7) can be written as a product of the generators *r*, *t*, and δ (using only positive powers, in fact). Since T(r), T(t), and $T(\delta)$ are known to lie in $GL(\mathbb{F}_8)$, repeated application of the lemma shows that T(h) lies in $GL(\mathbb{F}_8)$ for *all* $h \in SLF(7)$. Having drawn this conclusion, the lemma now shows that *T* is a group homomorphism.
- 4. *Proof that T is a bijection.* So far, we know that *T* is a group homomorphism mapping SLF(7) *into* GL(\mathbb{F}_8). *T* is actually *onto*, since the image of *T* contains $\langle T(r), T(t), T(\delta) \rangle$, which is the whole group GL(\mathbb{F}_8). Since SLF(7) and GL(\mathbb{F}_8) both have 168 elements, *T* must also be one-to-one.

Our proof that $PSL(2, 7) \cong GL(3, 2)$ is now complete. We leave it as a challenge for the reader to find an explicit description of the inverse bijection $T^{-1} : GL(\mathbb{F}_8) \to$ SLF(7).

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Angles as Probabilities

David V. Feldman and Daniel A. Klain

Almost everyone knows that the inner angles of a triangle sum to 180° . But if you ask the typical mathematician how to sum the solid inner angles over the vertices of a tetrahedron, you are likely to receive a blank stare or a mystified shrug. In some cases you may be directed to the Gram-Euler relations for higher-dimensional polytopes [4, 5, 7, 8], a 19th-century result unjustly consigned to relative obscurity. But the answer is really much simpler than that, and here it is:

The sum of the solid inner vertex angles of a tetrahedron T, divided by 2π , gives the probability that the orthogonal projection of T onto a random 2-plane is a triangle.

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How simple is that? We will prove a more general theorem (Theorem 1) for simplices in \mathbb{R}^n , but first consider the analogous assertion in \mathbb{R}^2 . The sum in radians of the angles of a triangle (2-simplex) T, when divided by the length π of the unit semicircle, gives the probability that the orthogonal projection of T onto a random line is a convex segment (1-simplex). Since this is *always* the case, the probability is equal to 1, and the inner angle sum for every triangle is the same. By contrast, a higher-dimensional *n*-simplex may project one dimension down either to an (n - 1)-simplex or to a lower-dimensional convex polytope having n + 1 vertices. The inner angle sum gives a measure of how often each of these possibilities occurs.

Let us make the notion of "inner angle" more precise. Denote by \mathbb{S}^{n-1} the unit sphere in \mathbb{R}^n centered at the origin. Recall that \mathbb{S}^{n-1} has (n-1)-dimensional volume (i.e., surface area) $n\omega_n$, where $\omega_n = \pi^{n/2} / \Gamma(1 + n/2)$ is the Euclidean volume of the unit ball in \mathbb{R}^n .

Suppose that *P* is a convex polytope in \mathbb{R}^n , and let *v* be any point of *P*. The solid inner angle $a_P(v)$ of *P* at *v* is given by

$$a_P(v) = \{ u \in \mathbb{S}^{n-1} \mid v + \epsilon u \in P \text{ for some } \epsilon > 0 \}.$$

Let $\alpha_P(v)$ denote the measure of the solid angle $a_P(v) \subseteq \mathbb{S}^{n-1}$, given by the usual surface area measure on subsets of the sphere. For the moment we are primarily concerned with values of $\alpha_P(v)$ when v is a *vertex* of P.

If *u* is a unit vector, then denote by P_u the orthogonal projection of *P* onto the subspace u^{\perp} in \mathbb{R}^n . Let *v* be a vertex of *P*. The projection v_u lies in the relative interior of P_u if and only if there exists $\epsilon \in (-1, 1)$ such that $v + \epsilon u$ lies in the interior of *P*. This holds if and only if *u* lies in the interior of $\pm a_P(v)$. If *u* is a random unit vector in \mathbb{S}^{n-1} , then

Probability[
$$v_u \in \text{relative interior}(P_u)$$
] = $\frac{2\alpha_P(v)}{n\omega_n}$. (1)

This gives the probability that v_u is no longer a vertex of P_u .

For *simplices* we now obtain the following theorem.

Theorem 1 (Simplicial Angle Sums). Let Δ be an *n*-simplex in \mathbb{R}^n , and let *u* be a random unit vector. Denote by p_{Δ} the probability that the orthogonal projection Δ_u is an (n-1)-simplex. Then

$$p_{\Delta} = \frac{2}{n\omega_n} \sum_{v} \alpha_{\Delta}(v), \qquad (2)$$

where the sum is taken over all vertices of the simplex Δ .

Proof. Since Δ is an *n*-simplex, Δ has n + 1 vertices, and a projection Δ_u has either *n* or n + 1 vertices. (Since Δ_u spans an affine space of dimension n - 1, it cannot have fewer than *n* vertices.) In other words, either exactly 1 vertex of Δ projects to the relative interior of Δ_u , so that Δ_u is an (n - 1)-simplex, or none of them do. By the law of alternatives, the probability p_{Δ} is now given by the sum of the probabilities (1), taken over all vertices of the simplex Δ .

The probability (2) is always equal to 1 for a 2-dimensional simplex (i.e., any triangle). The *regular* tetrahedron in \mathbb{R}^3 has solid inner angle measure

$$\alpha_T(v) = 3\arccos(1/3) - \pi$$

at each of its 4 vertices, so that (2) yields $p_{\Delta} \approx 0.351$. For more general 3-simplices (tetrahedra) the probability may take *any* value $0 < p_{\Delta} < 1$. To obtain a value of p_{Δ} close to 1 for a tetrahedron, consider the convex hull of an equilateral triangle in \mathbb{R}^3 with a point outside the triangle, but very close to its center. To obtain p_{Δ} close to 0, consider the convex hull of two skew line segments in \mathbb{R}^3 whose centers are very close together (forming a tetrahedron that is almost a parallelogram). Similarly, for $n \geq 3$ the solid vertex angle sum of an *n*-simplex varies within a range

$$0 < \sum_{v} \alpha_T(v) < \frac{n\omega_n}{2}$$

Equality at either end is obtained only if one allows for the degenerate limiting cases. These bounds were obtained earlier by Gaddum [2, 3] and Barnette [1], using more complicated methods.

Similar considerations apply to the solid angles at arbitrary faces of convex polytopes. Suppose that *F* is a *k*-dimensional face of a convex polytope *P*, for some *k* with $0 \le k \le \dim P$. The solid inner angle measure $\alpha_P(x)$ is the same at every point *x* in the relative interior of *F*. Denote this value by $\alpha_P(F)$. In analogy to (1), for any *x* in the relative interior of *F*, we have

Probability[
$$x_u \in \text{relative interior}(P_u)$$
] = $\frac{2\alpha_P(F)}{n\omega_n}$. (3)

Omitting cases of measures zero, this gives the probability that a proper face F is no longer a face of P_u . (Note that dim $F_u = \dim F$ for all directions u except a set of measure zero.) Taking complements, we have

Probability[
$$F_u$$
 is a proper face of P_u] = $1 - \frac{2\alpha_P(F)}{n\omega_n}$. (4)

For $0 \le k \le n - 1$, denote by $f_k(P)$ the number of k-dimensional faces of a polytope P. The sum of the probabilities (4) gives the expected number of k-faces of the projection of P onto a random hyperplane u^{\perp} ; that is,

$$\operatorname{Exp}[f_k(P_u)] = \sum_{\dim F = k} \left(1 - \frac{2\alpha_P(F)}{n\omega_n} \right) = f_k(P) - \frac{2}{n\omega_n} \sum_{\dim F = k} \alpha_P(F), \quad (5)$$

where the sums are taken over k-faces F of the polytope P.

If *P* is a convex polygon in \mathbb{R}^2 , then P_u is always a line segment with exactly 2 vertices, that is, $f_0(P_u) = 2$. In this case the expectation identity (5) yields the familiar

$$\sum_{v} \alpha_P(v) = \pi(f_0(P) - 2).$$

If *P* is a convex polytope in \mathbb{R}^3 , then P_u is a convex polygon, which always has exactly as many vertices as edges; that is, $f_0(P_u) = f_1(P_u)$. Therefore $\operatorname{Exp}[f_0(P_u)] = \operatorname{Exp}[f_1(P_u)]$, and the expectation identities (5) imply that

$$\frac{1}{2\pi} \sum_{\text{vertices } v} \alpha_P(v) - \frac{1}{2\pi} \sum_{\text{edges } e} \alpha_P(e) = f_0(P) - f_1(P) = 2 - f_2(P),$$

where the second equality follows from the classical Euler formula $f_0 - f_1 + f_2 = 2$ for convex polyhedra in \mathbb{R}^3 .

These arguments were generalized by Perles and Shephard [7] (see also [1], [4, p. 315a], [9]) to give a simple proof of the classical Gram-Euler identity for convex polytopes:

$$\sum_{F \subseteq \partial P} (-1)^{\dim F} \alpha_P(F) = (-1)^{n-1} n \omega_n, \tag{6}$$

where the sum is taken over all proper faces F of an n-dimensional convex polytope P. In the general case one applies the additivity of expectation to alternating sums over k of the identities (5), obtaining identities that relate the Euler numbers of the boundaries of P and P_u . Since the boundary of P is a piecewise-linear (n - 1)-sphere, while the boundary of P_u is a piecewise-linear (n - 2)-sphere, these Euler numbers are easily computed, and (6) follows.

The Gram-Euler identity (6) can be viewed as a discrete analogue of the Gauss-Bonnet theorem, and has been generalized to Euler-type identities for angle sums over polytopes in spherical and hyperbolic spaces [4, 5, 8], as well as for mixed volumes and other valuations on polytopes [6].

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Jump Home and Shift: An Acyclic Operation on Permutations

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Let $n \ge 1$ be fixed, and denote by S_n the set of all permutations of $[n] = \{1, ..., n\}$. We write a permutation π as a vector $\pi = (\pi(1), \pi(2), ..., \pi(n))$, and we say that the element $\pi(i)$ is in the *i*th position. We call the element $\pi(i)$ of the permutation a fixed element if $\pi(i) = i$. Moreover, let the home position of an element *k* be position

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